

XUM2AKSBL2T

Photoelectric sensors XU, photo electric sensor, miniature, thru beam, Sn=15 m, emitter, cable 2 m



Main

Range of product	Telemecanique Photoelectric sensors XU
Series name	General purpose single mode
Electronic sensor type	Photo-electric sensor transmitter
Sensor name	XUM
Sensor design	Miniature
Detection system	Thru beam
Material	Plastic
Supply circuit type	DC
Wiring technique	2-wire
Electrical connection	Cable
Cable length	2 m
Emission	Red thru beam
[Sn] nominal sensing distance	15 m need a receiver

Complementary

Enclosure material	PBT
Lens material	Modified polyarylate
Wire insulation material	PVC
Status LED	Supply on: 1 LED (orange)
[Us] rated supply voltage	12...24 V DC with reverse polarity protection
Supply voltage limits	10.2...26.4 V DC
Maximum voltage drop	<2 V
Current consumption	12 mA no-load
Maximum delay first up	100 ms
Depth	20 mm
Height	34 mm
Width	11 mm
Net weight	0.063 kg

Environment

Product certifications	CE UL RCM
Ambient air temperature for operation	-30...55 °C
Ambient air temperature for storage	-40...70 °C
Vibration resistance	+/- 1.5 mm (f = 10...55 Hz) 2 hours in each direction X, Y and Z conforming to IEC 60068-2-6
Shock resistance	500 m/s ² for X, Y, Z directions for 10 cycles (approx. 100 min) conforming to IEC 60068-2-27
IP degree of protection	IP67 conforming to IEC 60529

Packing Units

Package 1 Weight	63.000 g
Package 1 Height	160.000 mm
Package 1 width	20.000 mm
Package 1 Length	110.000 mm

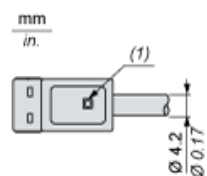
Offer Sustainability

REACH Regulation	 REACH Declaration
EU RoHS Directive	Compliant  EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	 Yes

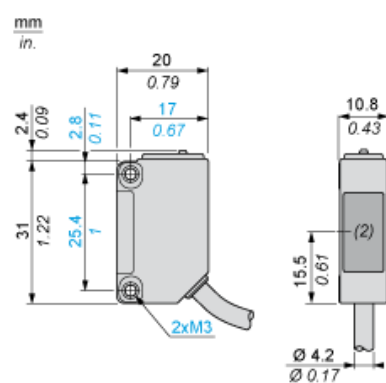
Dimensions

Transmitter. Pre-cable Version

Description



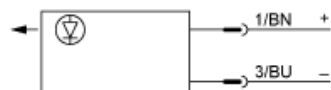
Dimensions



- (1) Power supply indicator (orange)
- (2) Transmission

Connections and Schema

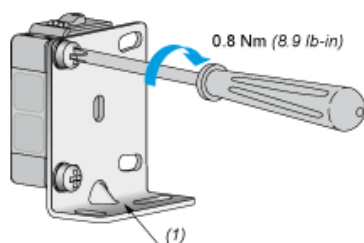
DC Transmitter



BN : Brown
BU : Blue

Mounting and Clearance

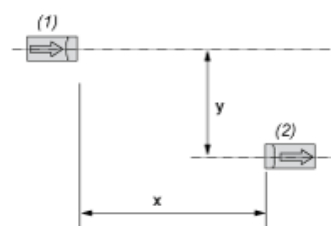
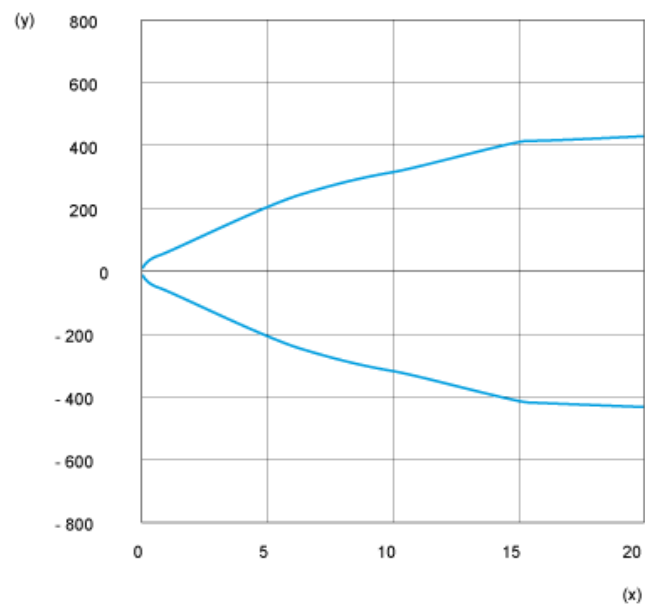
Tightening Torque



(1) Base mounting fixing bracket

Performance Curves

Thru-beam System



- (1) Transmitter
- (2) Receiver
- (y) Parallel movement in mm
- (x) Distance in m