

# ATV12HU22M2

variable speed drive ATV12 - 2.2kW - 3hp -  
200..240V - 1ph - with heat sink



## Main

Range of product	Altivar 12
Product or component type	Variable speed drive
Product destination	Asynchronous motors
Product specific application	Simple machine
Assembly style	With heat sink
Component name	ATV12
Quantity per set	Set of 1
EMC filter	Integrated
Built-in fan	With
Network number of phases	1 phase
[Us] rated supply voltage	200...240 V - 15...10 %
Motor power kW	2.2 kW
Motor power hp	3 hp
Communication port protocol	Modbus
Line current	24 A at 200 V 20.2 A at 240 V
Speed range	1...20
Transient overtorque	150...170 % of nominal motor torque depending on drive rating and type of motor
Asynchronous motor control profile	Sensorless flux vector control Quadratic voltage/frequency ratio Voltage/frequency ratio (V/f)
IP degree of protection	IP20 without blanking plate on upper part
Noise level	45 dB

## Complementary

Supply frequency	50/60 Hz +/- 5 %
Connector type	1 RJ45 (on front face) for Modbus
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	4800 bit/s 9600 bit/s 19200 bit/s 38400 bit/s
Number of addresses	1...247 for Modbus
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/Write multiple registers (23) 4/4 words Read device identification (43)
Prospective line Isc	1 kA
Continuous output current	10 A at 4 kHz
Maximum transient current	15 A for 60 s
Speed drive output frequency	0.5...400 Hz
Nominal switching frequency	4 kHz

Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Braking torque	Up to 70 % of nominal motor torque without braking resistor
Motor slip compensation	Adjustable Preset in factory
Output voltage	200...240 V 3 phases
Electrical connection	Terminal, clamping capacity: 5.5 mm², AWG 10 (L1, L2, L3, U, V, W, PA, PC)
Tightening torque	1.2 N.m
Insulation	Electrical between power and control
Supply	Internal supply for reference potentiometer: 5 V DC (4.75...5.25 V), <10 mA, protection type: overload and short-circuit protection Internal supply for logic inputs: 24 V DC (20.4...28.8 V), <100 mA, protection type: overload and short-circuit protection
Analogue input number	1
Analogue input type	Configurable current AI1 0...20 mA 250 Ohm Configurable voltage AI1 0...10 V 30 kOhm Configurable voltage AI1 0...5 V 30 kOhm
Discrete input number	4
Discrete input type	Programmable LI1...LI4 24 V 18...30 V
Discrete input logic	Negative logic (sink), > 16 V (state 0), < 10 V (state 1), input impedance 3.5 kOhm Positive logic (source), 0...< 5 V (state 0), > 11 V (state 1)
Sampling duration	20 Ms, tolerance +/- 1 ms for logic input 10 ms for analogue input
Linearity error	+/- 0.3 % of maximum value for analogue input
Analogue output number	1
Analogue output type	AO1 software-configurable voltage: 0...10 V, impedance: 470 Ohm, resolution 8 bits AO1 software-configurable current: 0...20 mA, impedance: 800 Ohm, resolution 8 bits
Discrete output number	2
Discrete output type	Logic output LO+, LO- Protected relay output R1A, R1B, R1C 1 C/O
Minimum switching current	5 mA at 24 V DC for logic relay
Maximum switching current	2 A 250 V AC inductive cos phi = 0.4 L/R = 7 ms logic relay 2 A 30 V DC inductive cos phi = 0.4 L/R = 7 ms logic relay 3 A 250 V AC resistive cos phi = 1 L/R = 0 ms logic relay 4 A 30 V DC resistive cos phi = 1 L/R = 0 ms logic relay
Acceleration and deceleration ramps	Linear from 0 to 999.9 s U S
Braking to standstill	By DC injection, <30 s
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t
Frequency resolution	Analog input: converter A/D, 10 bits Display unit: 0.1 Hz
Time constant	20 ms +/- 1 ms for reference change
Marking	CE
Operating position	Vertical +/- 10 degree
Height	142 mm
Width	105 mm
Depth	156.2 mm
Net weight	1.4 kg
Functionality	Basic
Specific application	Commercial equipment
Variable speed drive application selection	Commercial equipment Mixer Commercial equipment Other application Textile Ironing
Motor starter type	Variable speed drive

## Environment

Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 2...16 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 4...16 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <10 m
Product certifications	C-Tick CSA NOM UL GOST
Vibration resistance	1 gn (f = 13...200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 3...13 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6
Shock resistance	15 gn conforming to EN/IEC 60068-2-27 for 11 ms
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3 5...95 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for storage	-25...70 °C
Ambient air temperature for operation	-10...50 °C protective cover from the top of the drive removed 50...60 °C with current derating 2.2 % per °C
Operating altitude	> 1000...2000 m with current derating 1 % per 100 m <= 1000 m without derating

## Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Weight	1.753 kg
Package 1 Height	20 cm
Package 1 width	18 cm
Package 1 Length	20 cm
Unit Type of Package 2	S03
Number of Units in Package 2	2
Package 2 Weight	4.04 kg
Package 2 Height	30 cm
Package 2 width	30 cm
Package 2 Length	40 cm
Unit Type of Package 3	P06
Number of Units in Package 3	30
Package 3 Weight	65.95 kg
Package 3 Height	80 cm
Package 3 width	80 cm
Package 3 Length	60 cm

## Offer Sustainability

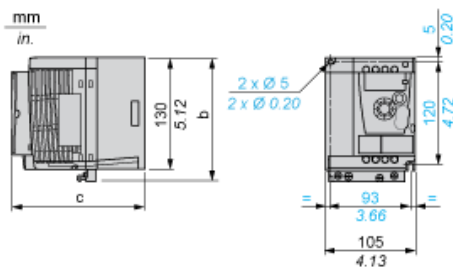
Sustainable offer status	Green Premium product
REACH Regulation	<a href="#">REACH Declaration</a>
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) <a href="#">EU RoHS Declaration</a>
Mercury free	Yes
RoHS exemption information	<a href="#">Yes</a>
China RoHS Regulation	<a href="#">China RoHS Declaration</a>
Environmental Disclosure	<a href="#">Product Environmental Profile</a>
Circularity Profile	<a href="#">End Of Life Information</a>
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

## Contractual warranty

Warranty	18 months
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Dimensions

Drive without EMC Conformity Kit



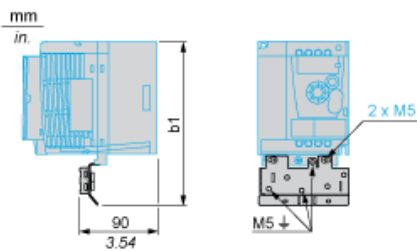
Dimensions in mm

b	c
142	156.2

Dimensions in in.

b	c
5.59	6.15

Drive with EMC Conformity Kit



Dimensions in mm

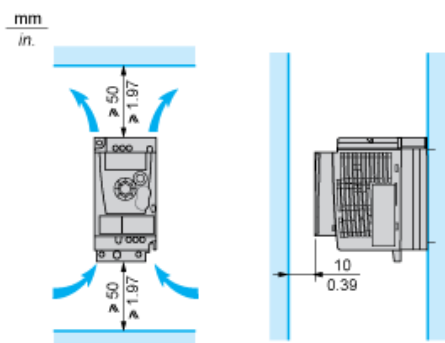
b1
188.2

Dimensions in in.

b1
7.41

## Mounting Recommendations

### Clearance for Vertical Mounting



### Mounting Type A



### Mounting Type B



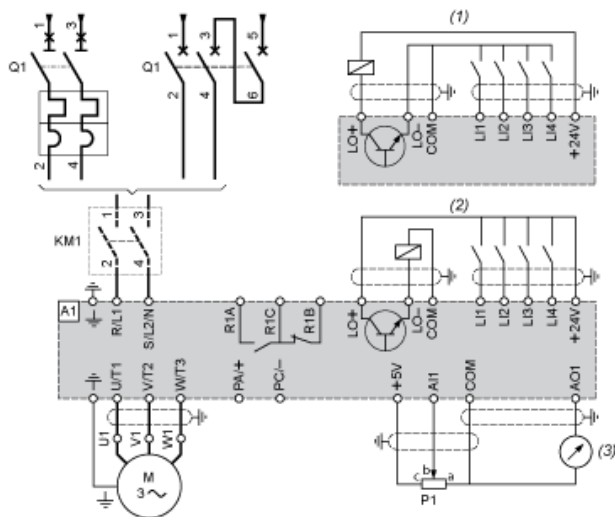
Remove the protective cover from the top of the drive.

### Mounting Type C



Remove the protective cover from the top of the drive.

## Single-Phase Power Supply Wiring Diagram



- A1 Drive  
KM1 Contactor (only if a control circuit is needed)  
P1 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum).  
Q1 Circuit breaker  
(1) Negative logic (Sink)  
(2) Positive logic (Source) (factory set configuration)  
(3) 0...10 V or 0...20 mA

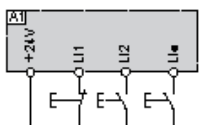
## Recommended Schemes

### 2-Wire Control for Logic I/O with Internal Power Supply



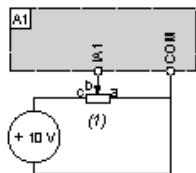
- L11 : Forward  
L1• : Reverse  
A1 : Drive

### 3-Wire Control for Logic I/O with Internal Power Supply



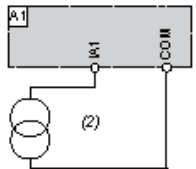
- L11 : Stop  
L12 : Forward  
L1• : Reverse  
A1 : Drive

## Analog Input Configured for Voltage with Internal Power Supply



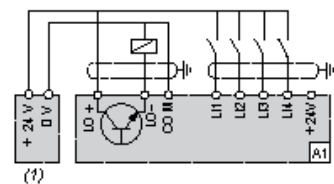
- (1) 2.2 k $\Omega$ ...10 k $\Omega$  reference potentiometer  
A1 : Drive

## Analog Input Configured for Current with Internal Power Supply



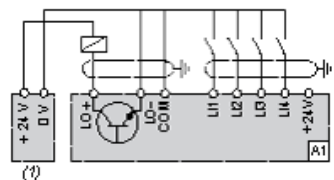
- (2) 0-20 mA 4-20 mA supply  
A1 : Drive

## Connected as Positive Logic (Source) with External 24 vdc Supply



- (1) 24 vdc supply  
A1 : Drive

## Connected as Negative Logic (Sink) with External 24 vdc supply



- (1) 24 vdc supply  
A1 : Drive



## Torque Curves



- 1 : Self-cooled motor: continuous useful torque (1)
- 2 : Force-cooled motor: continuous useful torque
- 3 : Transient overtorque for 60 s
- 4 : Transient overtorque for 2 s
- 5 : Torque in overspeed at constant power (2)

(1) For power ratings  $\leq 250$  W, derating is 20% instead of 50% at very low frequencies.

(2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.